

Announcements

1) Colloquium Wednesday,
2070 CB, 3-4
on Applied Math

2) HW - on #3, you
can use the formulae

$$(AB)^t = B^t A^t$$

$$(A^t)^t = A$$

On #4, your answers
are most efficiently expressed
in 2×2 "blocks":

$$A \in M_4(\mathbb{C})$$

$$A = \begin{bmatrix} A_{1,1} & A_{1,2} \\ A_{2,1} & A_{2,2} \end{bmatrix}$$

with $A_{i,j}$'s in $M_2(\mathbb{C})$

What we know:

Every linear transformation between finite-dimensional vector spaces over \mathbb{F} can be expressed as a matrix (basis dependent).

Any change-of-basis transformation may be represented as an invertible matrix.

Which matrices are the
nicest to work with
(while not being completely
trivial)?
i.e., invertibility?

Diagonal matrices!

Example 1: (2×2 inverse)

Let $A \in M_2(\mathbb{C})$. Then

if A is invertible and

$$A = (a_{i,j})_{i,j=1}^2, \text{ then}$$

$$A^{-1} = \frac{1}{a_{1,1}a_{2,2} - a_{1,2}a_{2,1}} \begin{bmatrix} a_{2,2} - a_{1,2} \\ -a_{2,1} & a_{1,1} \end{bmatrix}$$

the determinant

Example 2: If

A is an $n \times n$ diagonal matrix and if A is invertible, then if

$$A = \begin{bmatrix} a_1 & & & 0 \\ & a_2 & & \\ 0 & & \ddots & a_n \end{bmatrix},$$

$$A^{-1} = \begin{bmatrix} \frac{1}{a_1} & & & 0 \\ & \frac{1}{a_2} & & \\ 0 & & \ddots & \frac{1}{a_n} \end{bmatrix}$$

Invertibility of a
diagonal matrix is

Completely determined

by whether the

a_{ii} 's are zero or

not.

All nonzero = invertible.

Otherwise, not invertible.

Definition: (matrix norm)

If V and W are both

finite-dimensional normed

linear spaces over \mathbb{C} (or \mathbb{R}),

then if $T: V \rightarrow W$ is

linear and $\|\cdot\|_V$ and $\|\cdot\|_W$

are the norms on V and

W , respectively

We can define

$$\|T\| = \max_{\substack{\|x\|_h \leq 1 \\ x \in V}} \|Tx\|_w$$

This is a norm on $\mathcal{L}(V, W)$.

"Max" is a consequence
of finite-dimensionality.

We only care about

$$\|\cdot\|_r = \|\cdot\|_\omega = \|\cdot\|_2$$

in this class, although

$$\|\cdot\|_1 \text{ and } \|\cdot\|_\infty \text{ are}$$

also interesting.

Observations: (diagonals
in standard basis)

$$A \in M_n(\mathbb{C}),$$

$$A = \begin{bmatrix} a_1 & & & 0 \\ 0 & a_2 & & \\ & & \ddots & 0 \\ & & & a_n \end{bmatrix},$$

$$\|A\| = \max_{1 \leq i \leq n} |a_{ii}|$$

To see this,

$$\begin{aligned}\|Ae_i\|_2 &= \|a_i e_i\|_2 \\ &= |a_i| \|e_i\|_2.\end{aligned}$$

This says

$$\|A\| \geq \max_{1 \leq i \leq n} |a_i|$$

Conversely, if $\|h\|_2 = 1$,

$$h = \sum_{i=1}^n \beta_i e_i \text{ for some}$$

$$\beta_i \in \mathbb{C}, \quad 1 \leq i \leq n,$$

$$\|Ah\|_2^2 = \sum_{i=1}^n |a_i \beta_i|^2$$

$$= \sum_{i=1}^n |a_i|^2 |\beta_i|^2$$

$$\leq \max_{1 \leq i \leq n} |a_i|^2 \sum_{i=1}^n |\beta_i|^2$$

$\underbrace{\phantom{\sum_{i=1}^n |\beta_i|^2}}$

= 1 since

$$\|h\|_2 = 1$$

$$= \max_{1 \leq i \leq n} |a_i|^2$$

This shows

$$\|A\| \leq \max_{1 \leq i \leq n} \|A h_i\|_2.$$

Combining both inequalities,

$$\|A\| = \max_{1 \leq i \leq n} \|A h_i\|_2.$$

Example 3 :

Let $A = \begin{bmatrix} 2 & 1 \\ 1 & 8 \end{bmatrix}$.

Then

$$A = SDS^{-1}$$

with

$$D = \begin{bmatrix} 5+\sqrt{10} & 0 \\ 0 & 5-\sqrt{10} \end{bmatrix}$$

$$S = \begin{bmatrix} -3-\sqrt{10} & 1 \\ 1 & 3+\sqrt{10} \end{bmatrix}$$

We get that

$$\|A\| = \|D\| = 5 + \sqrt{10}$$

$$A^{-1} = S D^{-1} S^{-1}, D^{-1} = \begin{bmatrix} \frac{1}{5+\sqrt{10}} & 0 \\ 0 & \frac{1}{5-\sqrt{10}} \end{bmatrix}$$

First Question: When

can we write

$A \in M_n(\mathbb{C})$ as

$$A = SDS^{-1}$$

for some diagonal matrix D ?

Definition: (eigenvalues, eigenvectors) A complex number λ is said to be an eigenvalue

of $A \in M_n(\mathbb{C})$ if

$\exists \quad v \in \mathbb{C}^n, \quad v \neq (0, 0, \dots, 0)$

$$Av = \lambda v$$

The vector v is called
an **eigenvector** for the
eigenvalue λ .

Note: λ could be zero,

but v must always be
nonzero!

Theorem: (eigenspace)

Let λ be an eigenvalue
of $A \in M_n(\mathbb{C})$. Then

$$\{v \in \mathbb{C}^n \mid Av = \lambda v\} = W_\lambda$$

is a subspace of \mathbb{C}^n ,

called the eigenspace

associated to λ .

Proof:

Subspace test!

1) $\begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \in W_\lambda$ since

$$A \left(\begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \right) = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

2) If $v \in W_\lambda$, $\alpha \in \mathbb{C}$,

$$A(\alpha v) = \alpha A(v)$$

$$= \alpha \gamma v$$

$$= \gamma (\alpha v)$$

$$\Rightarrow \alpha v \in W_\lambda$$

3) If $\omega, v \in W_\lambda$,

$$A(\omega + v) = A(\omega) + A(v)$$

$$= \lambda \omega + \lambda v$$

$$= \lambda (\omega + v)$$

$\Rightarrow \omega + v \in W_\lambda$



Equivalence

If $A\mathbf{v} = \lambda\mathbf{v}$ ($\mathbf{v} \neq \mathbf{0}_r$),

then $A\mathbf{v} - \lambda\mathbf{v} = \mathbf{0}_r$.

This is equivalent to

$$(A - \lambda I_n) \mathbf{v} = \mathbf{0}_r$$

This says

$$\ker(A - \lambda I_n) \neq \{0\},$$

so $A - \lambda I_n$ is not

invertible. Conversely,

if $A - \lambda I_n$ is not

invertible, then $\exists v \in \mathbb{C}^n$,

$$v \neq 0, (A - \lambda I_n)v = 0_v$$

$\Rightarrow \lambda$ is an eigenvalue for A .

In order to quickly tell whether $A - \lambda I_n$ is invertible, we will develop the determinant.